

# Efficient First-Order Algorithms for Adaptive Signal Denoising

**Dmitrii Ostrovskii**<sup>\*</sup>    Zaid Harchaoui<sup>†</sup>

<sup>\*</sup>INRIA Paris, Ecole Normale Supérieure

<sup>†</sup>University of Washington

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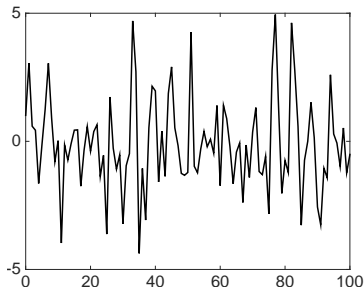
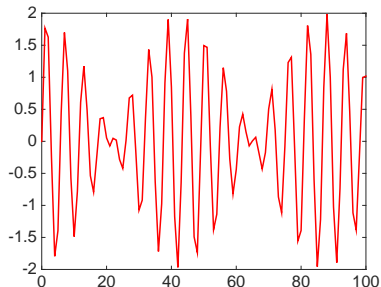
Stockholm

# Signal denoising problem

Recover discrete-time **signal**  $x = (x_\tau) \in \mathbb{C}^{2n+1}$  from noisy **observations**

$$y_\tau = x_\tau + \sigma \xi_\tau, \quad \tau = -n, \dots, n,$$

where  $\xi_\tau$  are i.i.d. standard Gaussian random variables.



**Difficulty: unknown structure**

# Adaptive denoising: background\*

**Linear time-invariant estimator:** convolution of  $y$  with filter  $\varphi \in \mathbb{C}^{n+1}$ :

$$\hat{x}_t = [\varphi * y]_t := \sum_{0 \leq \tau \leq n} \varphi_\tau y_{t-\tau}, \quad 0 \leq t \leq n,$$

- Suppose  $x$  satisfies discrete ODE (sines, polynomials, exponentials):

$$P(\Delta)x \approx 0,$$

where  $[\Delta x]_t := x_{t-1}$ , and operator  $P(\Delta) = \sum_{k=1}^d p_k \Delta^k$  is **unknown**.

- Then there **exists**  $\varphi^\circ$  with near-optimal risk and small  $\ell_1$ -norm of Discrete Fourier transform  $\mathcal{F}_n[\varphi^\circ]$ :

$$\|\mathcal{F}_n[\varphi^\circ]\|_1 \leq \frac{r}{\sqrt{n+1}}, \quad r = \text{poly}(\text{deg}(P)).$$

**Goal:** construct **adaptive filter**  $\hat{\varphi} = \hat{\varphi}(y)$  with similar properties to  $\varphi^\circ$ .

\*[Juditsky and Nemirovski, 2009, 2010; Harchaoui et al., 2015; Ostrovsky et al., 2016]

# Estimators

$$\begin{aligned} & \text{minimize } \text{Res}_p(\varphi) := \left\| \mathcal{F}_n[\mathbf{y} - \varphi * \mathbf{y}]_n^{2n} \right\|_p \\ & \text{subject to } \varphi \in \Phi(r) := \left\{ \|\mathcal{F}_n[\varphi]\|_1 \leq \frac{r}{\sqrt{n+1}} \right\}. \end{aligned}$$

**Least Squares** [Ostrovsky et al., 2016]:

$p = 2$  ( $\Rightarrow \ell_2$ -loss guarantees)

**Uniform Fit** [Harchaoui et al., 2015]:

$p = \infty$  ( $\Rightarrow \ell_\infty$ -loss guarantees)

- 😊 **simple constraint:** proximal mapping computed in  $O(n)$ ;
- 😊 **first-order oracle:** computed in  $O(n \log n)$  by reducing to FFT;
- 😊 **low accuracy:** *are crude approximate solutions sufficient?*

**First-order methods**

# Strategies

Fourier-domain:  $u := \mathcal{F}_n[\varphi]$ ,  $b = \mathcal{F}_n[[y]_n^{2n}]$ ,  $\mathcal{A}u := \mathcal{F}_n[[y * \varphi]_n^{2n}]$ .

**Least Squares:** quadratic problem on  $\ell_1$ -ball:

$$\min_{\|u\|_1 \leq \frac{r}{\sqrt{n+1}}} \|\mathcal{A}u - b\|_2^2.$$

- **Fast Gradient Method:**  $O(1/T^2)$  convergence after  $T$  iterations.\*

**Uniform Fit:** reduced to a **bilinear saddle-point** problem:

$$\min_{\|u\|_1 \leq \frac{r}{\sqrt{n+1}}} \|\mathcal{A}u - b\|_\infty = \min_{\|u\|_1 \leq \frac{r}{\sqrt{n+1}}} \max_{\|v\|_1 \leq 1} \langle v, \mathcal{A}u \rangle - \langle v, b \rangle.$$

- **Mirror Prox:**  $O(1/T)$  convergence after  $T$  iterations.\*

😊  $\ell_1$ -adapted geometry, dual certificates, adaptive step, proximal terms.

\*[Nesterov and Nemirovski, 2013; Juditsky and Nemirovski, 2011]

# Statistical accuracy: theoretical result

Let  $\|x\|_{n,p}$  be the “estimation norm” with the right scaling:

$$\|x\|_{n,p} = \left( \frac{1}{n+1} \sum_{t=n}^{2n} |x_t|^p \right)^{1/p}.$$

- **Exact solutions** [Harchaoui et al., 2015; Ostrovsky et al., 2016]:

$$\mathbb{P} \left\{ \|x - \hat{\varphi}_{LS} * y\|_{n,2} \geq C\sigma r \sqrt{\frac{\log(n/\delta)}{n+1}} \right\} \leq \delta,$$

$$\mathbb{P} \left\{ \|x - \hat{\varphi}_{UF} * y\|_{n,\infty} \geq C\sigma r^2 \sqrt{\frac{\log(n/\delta)}{n+1}} \right\} \leq \delta.$$

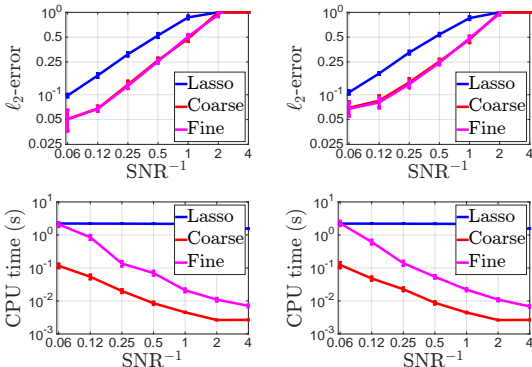
- We **extend** these results to **approximate solutions**:

## Theorem A

Approximate solutions  $\tilde{\varphi}$  with accuracy  $\epsilon_* = \sigma r$  for Uniform Fit and  $\epsilon_* = \sigma^2 r^2$  for Least Squares admit the same bounds as the exact ones.

# Experiment: early stopping

Comparison of  $\ell_2$ -loss and computation time in two scenarios: sum of sines with 4 random frequencies and 2 pairs of close frequencies (right)\*.



- **Coarse:** crude Least Squares solution with accuracy  $\varepsilon_* = \sigma^2 r^2$ ;
- **Fine:** near-optimal Least Squares solution with accuracy  $0.01\varepsilon_*$ ;
- **Lasso:** 10-fold oversampled Lasso estimator [Bhaskar et al., 2013].

Code available at <https://github.com/ostrodmitt/AlgoRec>

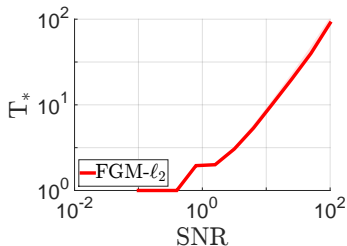
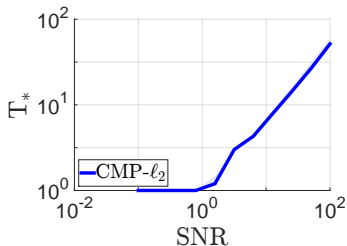
# Algorithmic complexity

## Theorem B

To reach the statistical accuracy  $\varepsilon_*$ , in each case it is sufficient to perform

$$T_* = O(\text{PSNR} + 1)$$

steps of the corresponding algorithm.



Iteration at which accuracy  $\varepsilon_*$  is attained **experimentally** on the sum of sines with 4 random frequencies: Uniform Fit (left), Least Squares (right).



**Thank you and see you at poster B#51**

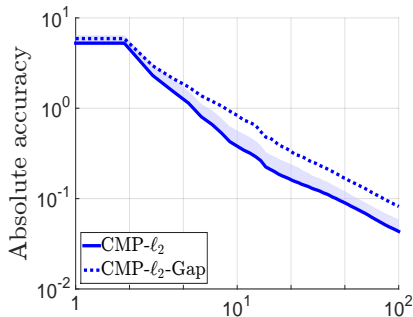
*Where I will also show how to solve some non-smooth problems in  $O(1/T^2)$ .*

# References

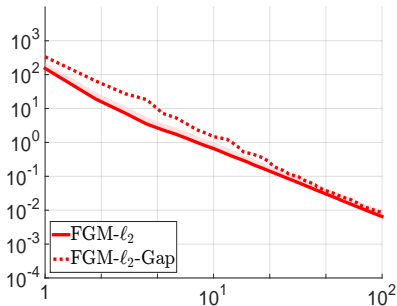
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# Convergence: numerical experiment

Constrained uniform-fit  
(Mirror Prox)



Constrained least-squares  
(Fast Gradient Method)



Convergence of the residual (95% upper confidence bound) for a sum of  $s = 4$  sinusoids with random frequencies and amplitudes, SNR = 4.

**Dashed:** online accuracy bounds via the dual certificate.