

# Structure-Blind Signal Recovery

Dmitry Ostrovsky\*

Zaid Harchaoui†

Anatoli Juditsky\*

Arkadi Nemirovski‡

\*Université Grenoble Alpes

†University of Washington

‡Georgia Tech

## Problem

► **Discrete-time signal**  $x = [x_{-T}, \dots, x_0, \dots, x_T]$  is observed with i.i.d. Gaussian noise:

$$y_\tau = x_\tau + \sigma \xi_\tau, \quad -T \leq \tau \leq T.$$

► **Full recovery**: recover the whole signal  $x$ , the loss is  $\|\hat{x} - x\|_2$ .

► **Pointwise recovery**: recover one sample  $x_t$  at some  $t \in \mathbb{Z}$ , the loss is  $|x_t - \hat{x}_t|$ .

► **Linear estimators**:  $\hat{x}_t^\varphi := \sum_{\tau} \varphi_\tau y_{t-\tau}$ .

## Structure-blind recovery

**Theorem** (Ibragimov and Khasminskii, 1984; Donoho, 1990)

Let a set  $\mathcal{X} \subset \mathbb{R}^{2T+1}$  be compact, symmetric, and convex.

► The minimax, over  $x \in \mathcal{X}$ , risk of recovering  $x_t$  is attained by a **linear** estimator  $\varphi^*$

► If  $\mathcal{X}$  is known,  $\varphi^*$  can be found, along with its confidence interval, by **cvx optim** over  $\mathcal{X}$ .

What if the set  $\mathcal{X}$  is unknown? Can we “mimick” the “oracle”  $\varphi^*$ ?

**Example.** Let  $\mathcal{X}$  be a subspace,  $\dim(\mathcal{X}) = s \ll T$ .

► For sure there exists an estimator  $\varphi = \varphi(\mathcal{X})$  with  $|\hat{x}_t^\varphi - x_t| = \mathcal{O}_\mathbb{P}(\sqrt{s/T})$ .

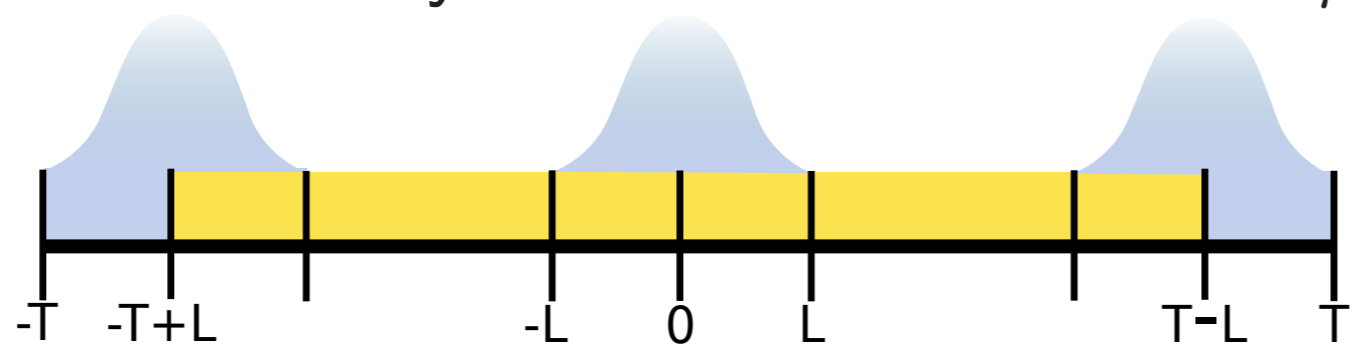
► But we don't know  $\mathcal{X}$  and hence cannot compute  $\varphi$ .

## Linear time-invariant filtering

Write  $\varphi \in \mathbf{B}_L$  if  $\varphi$  vanishes outside  $[-L, L]$  for some  $L \leq T$ .

Then one can estimate  $x_t$  in the **central region** around  $t = 0$  by **convolution** with such  $\varphi$ :

$$\hat{x}_t^\varphi = \sum_{|\tau| \leq L} \varphi_\tau y_{t-\tau} = [\varphi * y]_t, \quad |t| \leq T - L.$$



## Recoverable signals

For the sake of simplicity, let us assume that we want to estimate  $x_0$ .

**Definition.**  $x$  is  **$(T, \rho)$ -recoverable** at  $t = 0$  if there is a filter  $\varphi^{\text{oracle}} \in \mathbf{B}_L$ ,  $L = \mathcal{O}(T)$ , which has an  $\mathcal{O}(1/\sqrt{T})$  error of recovering  $x_\tau$  in the  $T - L$  neighbourhood of  $t = 0$ :

$$\mathbb{E}^{1/2} |x_\tau - [\varphi^{\text{oracle}} * y]_\tau|^2 \leq \frac{\sigma \rho}{\sqrt{T}}, \quad |\tau| \leq T - L,$$

As a consequence, in this neighbourhood w.h.p. one has  $\|x - \varphi^{\text{oracle}} * y\|_2 \leq C \sigma \rho$ .

► By simple algebra this is equivalent, up to a small constant, to:

1. **small  $\ell_2$ -norm of the oracle**:  $\|\varphi^{\text{oracle}}\|_2 \leq \frac{\rho}{\sqrt{T}}$ ;

2. **reproduction of the signal**:  $|x_\tau - [\varphi^{\text{oracle}} * x]_\tau| \leq \frac{\sigma \rho}{\sqrt{T}}$ ,  $|\tau| \leq T - L$ .

► Of course, we can introduce the same assumption for any  $t \in \mathbb{Z}$ .

## Example: estimation of smooth curves

Consider the problem of estimating a smooth function  $f : [0, 1] \rightarrow \mathbb{R}$

$$y_\tau = f(\tau/n) + \sigma \xi_\tau, \quad \tau = -n, \dots, n, \quad \xi \sim \mathcal{N}(0, I_n).$$

The classical **kernel estimator**  $\hat{f}_t$  of  $f(t)$  with bandwidth  $h$  is

$$\hat{f}_t = \sum_{|\tau| \leq n} \frac{1}{2nh} K\left(\frac{t - \tau/n}{h}\right) y_\tau,$$

and  $K(t) : [-1, 1] \rightarrow \mathbb{R}$  is a **kernel** such that

$$\int_{-1}^1 K(t) dt = 1, \quad \int_{-1}^1 K^2(t) dt = \rho^2 < \infty.$$

Let  $x_\tau = f(\tau/n)$ ,  $\tau = -n, \dots, n$ , and let  $T = [nh]$ . Then, the kernel estimator can be rewritten for  $|t| \leq n - T$ :

$$\hat{x}_t = \hat{f}(t/n) = (\varphi * y)_t, \quad \varphi_\tau = \frac{1}{T} K\left(\frac{\tau}{T}\right), \quad \tau = -T, \dots, T.$$

Note that for big enough  $T$  the  $\ell_2$ -norm of  $\varphi$  satisfies  $\|\varphi\|_2 \sim \frac{\rho}{\sqrt{T}}$ , and if bandwidth  $h$  is “properly chosen”, the bias of the estimator is  $\frac{\sigma \rho}{\sqrt{T}}$ .

## Main assumption: approximate shift-invariance

A set  $\mathcal{S}$  of signals on  $\mathbb{Z}$  is called **shift-invariant** if it is preserved under the shift  $x_t \mapsto x_{t-1}$ .

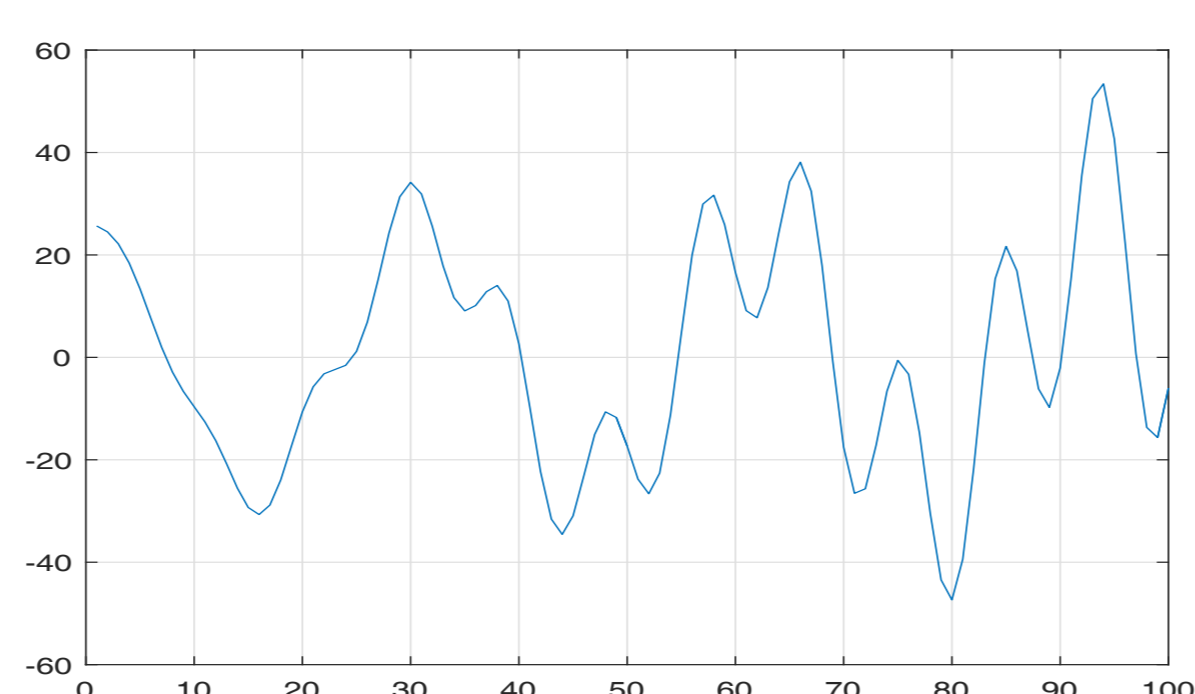
**Approximate Shift-Invariance Assumption (ASIA)** at  $t = 0$ :

$x$  is close to an (unknown) **shift-invariant subspace**  $\mathcal{S} \subset \mathbb{C}^{\mathbb{Z}}$  of dimension  $s \leq T$ .

Specifically,  $x = x^{\mathcal{S}} + \delta$ , where  $x^{\mathcal{S}} \in \mathcal{S}$  and  $\|[\delta]_{-T}^T\|_2 \leq \varkappa \sigma$ .

**SIA  $\Leftrightarrow$  exp. polynomials.**  $x$  satisfying SIA can be approximated by an exponential polynomial

$$p_\tau = \sum_{k=1}^s c_k \tau^{r_k} e^{i \omega_k \tau}$$



An exponential polynomial with  $s = 2$

**SIA  $\Rightarrow$  recoverable.**  $x$  satisfying SIA is  $(T, \rho)$ -recoverable at  $t = 0$  with  $\rho = (1 + \varkappa)\sqrt{s}$ .

## Example: sum of harmonic oscillations

Sum of  $s$  harmonic oscillations  $x_\tau = \sum_{k=1}^s c_k e^{i \omega_k \tau}$  satisfies ASIA with  $\varkappa = 0 \Rightarrow \rho = \sqrt{s}$ .

## What we want

Estimator  $\hat{\varphi}$  with the following properties:

► error of  $\hat{\varphi}$  of the same order as for  $\varphi^{\text{oracle}}$ ; ►  $\hat{\varphi}$  can be efficiently computed.

## Discrete Fourier transform

Let  $F_m$  be the  $(2m+1) \times (2m+1)$  DFT matrix:

$$[F_m]_{jk} = \frac{1}{\sqrt{2m+1}} \exp\left(\frac{2\pi i j k}{2m+1}\right).$$

For  $x = [x_{-m}; \dots; x_m]$  consider the Fourier norms

$$\|x\|_p^F := \|F_m x\|_p.$$

## Estimator: spectral regularization

$\hat{x} := \hat{\varphi} * y$  where  $\hat{\varphi} \in \mathbf{B}_{2L}$  is an optimal solution to:

$$\min_{\varphi \in \mathbf{B}_{2L}} \|y - \varphi * y\|_2^2 + \lambda \|\varphi\|_1^F, \quad (\text{Pen-}\ell_2)$$

► Favourable structure: efficiently solved by Mirror Prox or Accelerated Gradient Descent.

## Main result

**Theorem 1** Under ASIA at  $t = 0$ , estimator (Pen- $\ell_2$ ) with  $\lambda \asymp \sigma^2 \sqrt{T} \log(T)$  achieves

$$|x_0 - [\hat{\varphi} * y]_0| \leq \frac{C \sigma \rho}{\sqrt{T}} (\rho^2 + \rho \sqrt{\log T}).$$

$$\|x - \hat{\varphi} * y\|_2 \leq C \sigma \rho (\rho + \sqrt{\log T}).$$

## Discussion I: uniform fit estimator

Another estimator studied in [J. & N., 2009], and its  $\rho$ -adaptive version in [H. et al., 2015]

$$\min_{\varphi \in \mathbf{B}_{2L}} \|y - \varphi * y\|_\infty^F$$

such that  $\|\varphi\|_1^F \leq \frac{\rho^2}{\sqrt{T}}$ .

**Theorem** (H. et al., 2009). If  $x$  is  $(T, \rho)$ -recoverable at  $t = 0$ ,  $\hat{\varphi}$  as above satisfies

$$|x_0 - [\hat{\varphi} * y]_0| \leq \frac{C \sigma \rho}{\sqrt{T}} (\rho^3 \sqrt{\log T}).$$

$$\|x - \hat{\varphi} * y\|_2 \leq C \sigma \rho (\rho^3 \sqrt{\log T}).$$

► Higher adaptation price **but** ASIA is not needed, recoverability is enough.

## Discussion II: sum of harmonic oscillations

For a sum of  $s$  harmonic oscillations, we obtain, **with no frequency separation assumption**,

$$\mathbb{E}^{1/2} \|\hat{x} - x\|_2^2 \leq \tilde{\mathcal{O}}\left(\frac{\sigma s}{\sqrt{T}}\right)$$

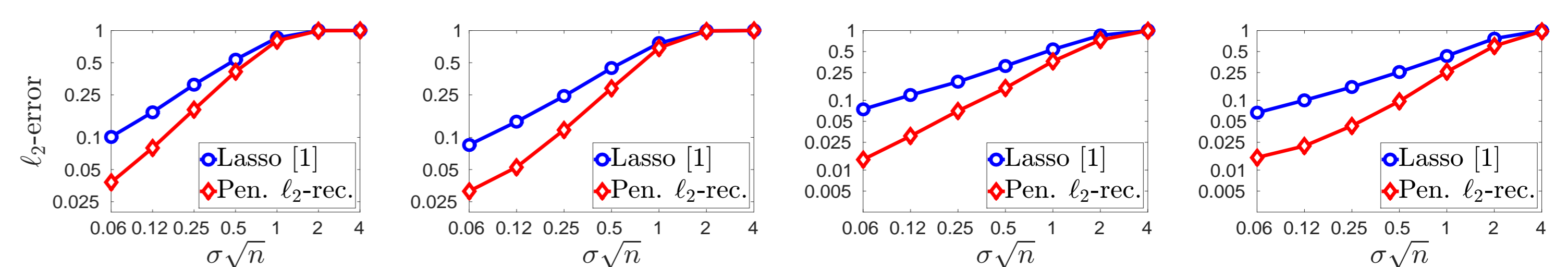
► Assuming frequency separation,  $s$  can be replaced by  $\sqrt{s}$  for the Lasso estimator of [Tang et al.]

► Our result is more general: it admits exponential polynomials instead of harmonic oscillations with separated frequencies.

## Numerical experiments

We present the results of Monte-Carlo experiments on simulated data, comparing the penalized  $\ell_2$ -estimator with the Lasso [Tang et al.].

► Harmonic oscillations with random frequencies (*RandomFreq*) and random pairs of close frequencies (*CoherentFreq*) in 1-D and 2-D.



Signal and image denoising in scenarios *RandomFreq*, *CoherentFreq*, *RandomFreq-2D*, *CoherentFreq-2D*.

► In scenario *DimensionReduction* we consider the single-index regression model:

$$f(t/n) = g(\theta^T t/n), \quad g(\cdot) \in \mathcal{S}_\beta^1(1). \quad (1)$$

where  $\mathcal{S}_\beta^1(1) = \{g : \mathbb{R} \rightarrow \mathbb{R}, \|g^{(\beta)}(\cdot)\|_2 \leq 1\}$  is the Sobolev ball of smooth periodic functions on  $[0, 1]$ , and the unknown structure is formalized as the direction  $\theta$ .

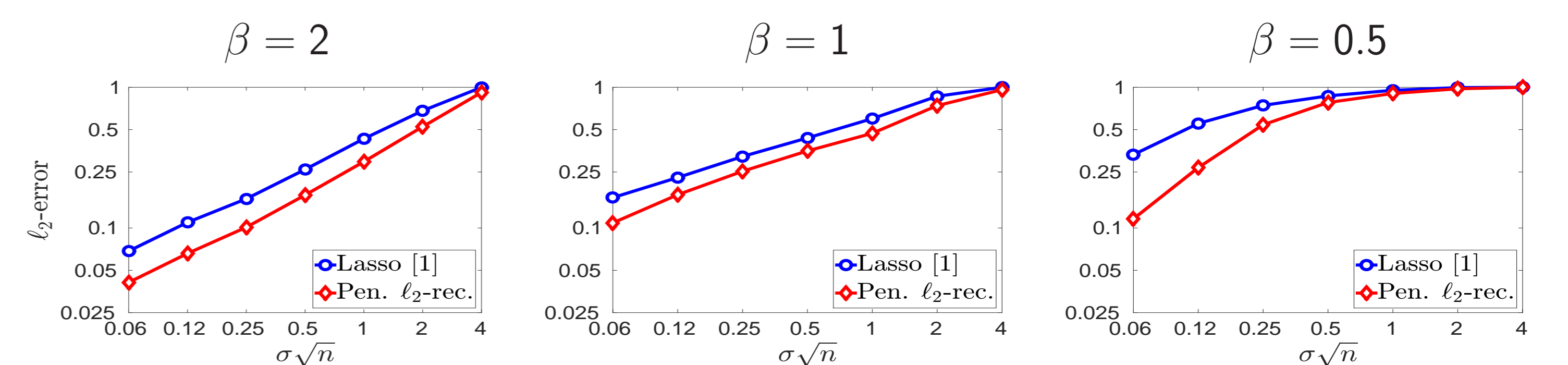


Image denoising in *DimensionReduction* scenario; smoothness decreases left to right.

## Bandwidth adaptation

► For **each point**  $t$  of the grid, and for each bandwidth  $\{T_0 = 1, T_1 = 2, \dots, T_K = 2^K\}$ , compute a solution  $\hat{\varphi}_{T_k, t}$  of (Pen- $\ell_2$ ).

► Compute  $\hat{x}_t[T_k] = [\hat{\varphi}_{T_k, t} * y]_t$  and choose the “best” among them via Lepski's algorithm.

► To reduce the numerical cost, instead of proceeding point-wise, one can use block-wise update of filters, using the  $\ell_2$ -bound of Theorem 1.